Power scattering and absorption mediated by cloak/anti-cloak interactions: a transformation-optics route toward invisible sensors

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The suggestive idea of “cloaking” an electromagnetic sensor, i.e., strongly reducing its visibility (scattering) while maintaining its field-sensing (absorption) capabilities, has recently been proposed in the literature, based on scattering-cancellation, Fano-resonance, or transformation-optics approaches. In this paper, we explore an alternative transformation-optics-based route, which relies on the recently introduced concept of “anti-cloaking.” More specifically, our proposed approach relies on a suitable tailoring of the competing cloaking and anti-cloaking mechanisms, interacting in a two-dimensional cylindrical scenario. Via analytical and parametric studies, we illustrate the underlying phenomenology, identify the critical design parameters, and address the relevant optimality and trade-off issues, taking also into account the effect of material losses. Our results confirm the envisaged potentials of the proposed transformation-optics approach as an attractive alternative route to sensor cloaking. © 2010 Optical Society of America


1. INTRODUCTION
During the past few years, there has been a growing interest in the development of strategies and devices to achieve invisibility of objects to waves of various nature [electromagnetic (EM), acoustic, elastic, and matter]. With special reference to the EM case, among the most prominent approaches to passive “invisibility cloaking,” it is worth mentioning those based on scattering cancellation [1,2], anomalous localized resonances [3], transformation optics (TO) [4,5], inverse design of scattering optical elements [6], transmission-line networks [7], and tapered optical waveguides [8]. The reader is also referred to [9–12] for related experimental studies at microwave and optical frequencies.

In the TO approach to cloaking, of particular interest for what follows, the rerouting of the impinging energy around the concealed object is first designed in a fictitious curved-coordinate space containing a “hole,” and it is subsequently translated into a conventionally flat Cartesian space, filled by an anisotropic and spatially inhomogeneous “transformation medium” that embeds the coordinate-mapping effects [4,5,13,14]. Starting from this basic concept, a variety of extensions and twists have been proposed, including the carpet cloak [15–20], open cloak [21], cloak at a distance [22], anti-cloak [23,24], superscatterer [25] and superabsorber [26], and invisible gateway [27], as well as the broad framework of “illusion optics” [28].

In connection with the anti-cloaking concept, directly related to the subject of this paper, it was shown in [23] that, in spite of the generally assumed impenetrability of an ideal cylindrical cloak shell [29–31] (implying a lossless, anisotropic, and spatially inhomogeneous medium, with extreme values of the constitutive parameters ranging from zero to infinity), field penetration in the cloaked region may actually occur in the presence of a suitably designed complementary double-negative (DNG) transformation cylindrical shell of “undoing” (partially or completely) the cloak transformation. Expanding upon this concept, in [24], we studied a more general scenario featuring a cloak and an anti-cloak separated by a vacuum layer and showed that: (i) anti-cloaking-type effects and interesting field tunneling phenomena may also be achieved with double-positive (DPS) or single-negative transformation media, thereby relaxing some of the practical feasibility limitations; (ii) besides the originally proposed “cloaking countermeasure” application in [23], alternative application scenarios may be envisaged for which a (multiply connected) region of space may be cloaked, while maintaining the capability of somehow “sensing” the outside field from the inside. A similar idea, within the suggestive framework of “sensor cloaking,” was recently explored in [32] (via a scattering-cancellation approach), in [33] (via a Fano-resonance-type approach), and in [34] (via a TO-based approach).

In this paper, we further elaborate on the above con-
cepts, exploring more in detail the possibility to apply them to sensor cloaking. In particular, for the same two-dimensional (2-D) scenario considered in [24], consisting of a metamaterial cylindrical target surrounded by a cloak and an anti-cloak separated by a vacuum gap, we present some analytical results and parametric studies aimed at gaining a deeper insight in the trade-off between power absorption and scattering for a slightly lossy target (mimicking the sensor loading effects). In this framework, we show that the cloak/anti-cloak interactions can be tailored so as to allow sensible power absorption by the target while still guaranteeing very weak overall scattering, thereby indicating an alternative TO-based route to sensor cloaking.

Accordingly, the rest of the paper is organized as follows. In Section 2, we introduce the problem geometry and formulation. In Section 3, we outline the general analytical solution and the relevant derivations. In Section 4, we illustrate and discuss some representative results from a comprehensive parametric study; and, in Section 5, we address some implementation-related issues. Finally, in Section 6, we provide some brief concluding remarks and hints for future research.

2. PROBLEM GEOMETRY AND STATEMENT

The scenario of interest is the same as the one considered in [24] and, as illustrated in Fig. 1, entails a four-layer cylindrical configuration of radii (1, 2, 3, 4) in the physical space (x, y, z). More specifically, such configuration features an innermost metamaterial cylindrical target of radius 1 (with electric permittivity ε1 and magnetic permeability μ1) surrounded by two transformation-medium layers separated by a vacuum gap and is obtained via a piecewise-linear radial coordinate mapping.

![Fig. 1. (Color online) Problem geometry: A homogeneous metamaterial circular-cylindrical target of radius 1, and constitutive parameters ε1 and μ1, surrounded by a cloak and anti-cloak cylindrical shells separated by a vacuum gap, in the actual physical space (x, y, z) [and associated cylindrical coordinate system (r, φ, z)].](image)


from an auxiliary fictitious space (x′, y′, z′) featuring a homogeneous circular cylinder with constitutive parameters ε1 and μ1 and radius R2>R1. The analytical expressions of the constitutive tensors characterizing the cloak and anti-cloak transformation media are systematically derived from the (derivative of) the mapping function f in Eq. (1) and are not reported here for brevity (see [24] for details). It can be observed that, letting to zero the small parameters Δ2 and Δ3 which parameterize the vanishing behavior of the coordinate transformation in Eq. (1), the outermost layer R2<r<R4 reduces to the standard invisibility cloak [9], while the internal layer R1<r<R2 reduces to an anti-cloak [23] (with constitutive parameters opposite in sign to those of the inner target). It was shown in [24] that the two competing cloak/anti-cloak effects can be tailored so as to create an effectively cloaked region in the vacuum gap R2<r<R3 while still being able to restore a non-negligible field in the (lossless) inner cylinder. Such a restored field may be interestingly used for sensing purposes, suggesting a novel route toward the sensor-cloaking idea. Therefore, it is of interest to study the scattering and absorption properties of the above configuration in the presence of a slightly lossy target in the inner region (r<R1) and to explore the role of the various parameters available.

3. ANALYTICAL RESULTS

A. General Solution

Assuming time-harmonic \(\exp(-i\omega t)\) transverse-magnetic plane-wave excitation (with unit-amplitude z-directed magnetic field) impinging from the positive x-direction, the relevant magnetic field in the four-layer configuration of Fig. 1 can be computed via our previously derived Fourier–Bessel expansion [24], based on the approaches originally proposed in \([29,30,35,36]\),

\[
\begin{align*}
H_z(r, \phi) &= \sum_{n=0}^{\infty} \left[ (\alpha_n^{(s)} + \delta_0^{(s)}) J_n[g(r)] + b_n^{(s)} Y_n[g(r)] \exp(in\phi) \right] \\
&\quad \text{where } \alpha_n^{(s)} = 1, \ldots, 5, R_{v-1} < r < R_v
\end{align*}
\]

In Eq. (2), \(J_n\) and \(Y_n\) denote the nth-order Bessel functions of the first and second kinds [37], respectively; \(R_0 = 0\) and \(R_5 = \infty\) are “dummy” parameters introduced for notational convenience; \(\delta_0\) is the Kronecker delta; and

\[
g(r) = \begin{cases} 
  k_0 r', & R_2 < r < R_3 \\
  \omega \sqrt{\epsilon'(r')} \mu'(r') f(r), & R < R_2, \ r > R_3,
\end{cases}
\]

where \(\epsilon'(r') = \epsilon_1 + \epsilon_2 U(r' - R_2)\) and \(\mu'(r') = \mu_1 + (\mu_0 - \mu_1) U(r' - R_2)\), with \(U\) denoting the unit-step function. Referring the reader to [24] for details on the procedure.
for computing the expansion coefficients $a_n^{(i)}$ and $b_n^{(i)}$, we
limit ourselves to summarize the final results that are instrumen-
tal for what follows:

\[ b_n^{(4,5)} = ia_n^{(5)}, \quad a_n^{(4)} = i^2 + ia_n^{(5)}, \quad b_n^{(1,2)} = 0, \quad a_n^{(2)} = a_n^{(1)}, \]

\[ a_0^{(1,3,5)} \sim b_0^{(3)} \sim O\left(\frac{1}{\log \Delta_3}\right), \]

\[ a_n^{(3)} \sim O\left(\frac{3^{|n|}}{\Delta_3^{2n}}\right), \quad a_n^{(3)} \sim b_n^{(3)} \sim O(\Delta_3^{n}), \]

\[ a_n^{(6)} \sim O(\Delta_3^{2n}), \quad n > 0, \]

where the Landau asymptotic notation $O(\ )$ is used, ne-
glecting irrelevant constants and higher-order terms. From
Eqs. (4)–(6), it is clear that, letting to zero $\Delta_2$ and $\Delta_3$
while maintaining their ratio $R_2$ finite, it is possible to ren-
ner all the expansion coefficients pertaining to the vac-
uum gap and exterior region vanishingly small while
keeping the (higher-order) coefficients pertaining to the
target region nonzero.

**B. Slightly Mismatched Target**

In the new sensor-cloaking scenario of interest, the inner
region $r < R_1$ is filled by an absorbing particle (modeling
a sensor or a detector) and, thus, different from [24], is
not matched with the surrounding anti-cloak. We therefore
begin by studying perturbatively the effects of a slightly
mismatched electrical permittivity,

\[ \bar{\epsilon}_1 = (1 + \Delta_x)^2 \epsilon_1, \]

of the target, with the vanishingly small term $\Delta_x$ parame-
terizing this mismatch. Denoting with an overbar the ex-
pansion coefficients in Eq. (2) pertaining to the mis-
matched configuration, and repeating the procedure in
[24], with the dependence on $\Delta_x$ parameterized via a first-
order Taylor expansion, we obtain

\[ \bar{a}_n^{(1)} = 0, \quad \bar{b}_n^{(4,5)} = i\bar{a}_n^{(5)}, \quad \bar{a}_n^{(4)} = i^2 + \bar{a}_n^{(5)}, \]

\[ \bar{b}_n^{(2)} \sim \bar{a}_n^{(1)} O(\Delta_x), \quad \bar{a}_n^{(2)} \sim \bar{a}_n^{(1)} [1 + O(\Delta_x)], \]

\[ \bar{a}_n^{(1)} \sim a_n^{(1)} \left( \begin{array}{c} \bar{z}_n^{(3,5)} \\ \bar{b}_n^{(3)} \\ b_n^{(3)} \end{array} \right) \left( \begin{array}{c} 1 + O_n \\ 1 + O_n \end{array} \right), \]

where

\[ O_n = \begin{cases} O(\Delta_x \log \Delta_3), & n = 0 \\ O(\Delta_x \Delta_3^{2n}), & n > 0. \end{cases} \]

In Eqs. (9) and (10), for a better understanding of the scal-
ing behaviors, the original (i.e., in the absence of mis-
match) expansion coefficients have been factored out. It is
readily observed that the mismatch affects primarily the
field transmitted in the target region, while the field in
the vacuum gap and the one scattered in the exterior
space maintain the vanishingly small character as in the
matched case. In particular, depending on ratio of the van-
ishingly small parameters $\Delta_x$ and $\Delta_3$, the higher-order
$a_n^{(6)}$ coefficients will exhibit an algebraically decaying
behavior. For instance, assuming $\Delta_x \sim O(\Delta_3^{2q})$ (with $q > 0$)
and $\Delta_2 \sim O(\Delta_3)$, it results from Eq. (10) [with Eq. (6)] that

\[ \bar{a}_n^{(1)} \sim O(\Delta_3^{2n/q-2q}), \quad n > q. \]

To sum up, the presence of a slightly mismatched target
does not affect the cloaking function, but it may affect the
anti-cloaking capability of restoring a field in the target
region since, besides the zeroth-order coefficient $a_0^{(1)}$
in Eq. (10) (which is still logarithmically vanishing as in
[24]), an infinite number of higher-order terms are now
generally lost [cf. Eq. (12)]. For increasing mismatch
levels, the anti-cloaking effect is progressively destroyed,
and the cloaking effect eventually prevails.

**C. Vanishing-Gap Limit**

We now move on to studying the effects of the vacuum gap
$R_2 < r < R_3$ which, in the new scenario of interest, is no
longer functional to creating a cloaked region, but it con-
stitutes an additional degree of freedom to tailor the
cloak/anti-cloak interactions. While its general effects in
the EM response are not easy to parameterize, it is par-
ticularly insightful to study the limiting case

\[ R_3 = (1 + \Delta_G)R_2, \]

where the term $\Delta_G$ parameterizes the vanishingly small
gap. Once again, proceeding as in [24], and parameteriz-
ing as a first-order Taylor expansion the dependence on
$\Delta_G$, we obtain for the relevant expansion coefficients in
the target and exterior regions

\[ a_n^{(1)} \sim \begin{cases} \frac{1}{1 + O(\Delta_G \log \Delta_3)^n}, & n = 0 \\ \frac{2i^n \gamma^{n} \epsilon_1}{\Delta_3^{2n}} \left( \begin{array}{c} \Delta_3^{n} \\ \Delta_2 \end{array} \right) + O(\Delta_3^{2n}) + O(\Delta_G), & n \neq 0, \end{cases} \]

\[ a_n^{(1)} \sim \begin{cases} O(\Delta_G \log^{-1} \Delta_3) + O(\Delta_G), & n = 0 \\ O(\Delta_3^{2n})[1 + O(\Delta_G)], & n \neq 0, \end{cases} \]

where

\[ \gamma = \sqrt{\frac{\epsilon_1 \mu_0}{\mu_1}} R_1(R_2 - R_1) \]

We observe that, in the vanishing-gap limit, the scattered-field
coefficients maintain their vanishingly small character [in fact, the zeroth-order terms vanish
now faster than logarithmically; cf. Eq. (15)]. In connec-
tion with the field transmitted in the target region [cf. Eq.
(14)], we point out that, besides the ($n \neq 0$)-th-order terms
for $\Delta_2 \sim O(\Delta_3)$, it is now possible to recover also the
zeroth-order term by letting $\Delta_G \rightarrow 0$ faster than $\log^{-1} \Delta_3$.
In fact, assuming $\Delta_2 = 0$ (i.e., $R_3 = R_2$), and enforcing the
continuity of the coordinate transformation in Eq. (1),
$f(R_2 = R_3^*)$, we obtain
\begin{align}
\frac{R_1 \Delta_2}{R_2 + \Delta_2 - R_1} &= \frac{R_4 \Delta_3}{R_4 + \Delta_3 - R_3},
\end{align}

which, for \( \Delta_{2,3} \to 0 \), implies

\begin{align}
\gamma &= \sqrt{\frac{\epsilon_0/(\mu_0)}{\epsilon_1/\mu_1}} \frac{\Delta_2}{\Delta_3}.
\end{align}

For the (trivial) case of a vacuum target \((\epsilon_1 = \epsilon_0, \mu_1 = \mu_0)\), this yields \(\alpha_n^{(5)} = i^n\) in Eq. (14), i.e., the anti-cloak perfectly compensates the cloak, restoring the impinging plane-wave, as in the original scenario presented in [23]. For materials other than vacuum, the field transmitted in the target is a distorted version of the incident one.

### D. Remarks

The two cases above (slightly mismatched target and vanishing gap) can readily be combined by substituting Eqs. (14) and (15) in Eq. (10). From the above results, in the sensor-cloaking scenario of interest, the vanishing-gap configuration appears particularly well suited, since it allows the recovery of the (otherwise logarithmically vanishing) zeroth-order terms of the transmitted field (and thus, in principle, a more effective power absorption) while keeping the scattered field vanishingly small (with a faster decay of the zeroth-order terms). These considerations are expected to hold also in the case of slightly lossy cloak/anti-cloak shells.

### 4. PARAMETRIC ANALYSIS

#### A. Generality and Observables

To complement the analytical results above, we carried out a series of parametric studies, aimed at identifying the “optimal” parameter configurations and possible trade-offs, within and beyond the limits \(\Delta_{2,3,G,c} \to 0\), and also in the more realistic case of slightly lossy cloak and anti-cloak. In our studies below, we utilize the analytical solution in Eq. (2) and compactly parameterize the EM response of the configurations in terms of the total scattering and absorption cross-sectional widths per unit length [33] (normalized to the vacuum wavelength \(\lambda_0\)),

\begin{align}
Q_s &= -\frac{2}{\pi} \sum_{n = -\infty}^{\infty} |\tilde{a}_n^{(5)}|^2, \quad Q_a = -\frac{2}{\pi} \sum_{n = -\infty}^{\infty} \|\tilde{a}_n^{(5)}\|^2 + \text{Re}[i^n a_n^{(6)}].
\end{align}

In the case of slightly lossy cloak and anti-cloak, for which the absorption cross-section \(Q_a\) is no longer representative of the power absorption of the target/sensor only, we consider the time-averaged power (per unit length along the \(z\)-axis) dissipated in the target region,

\begin{align}
P_a &= \frac{\omega}{2} \text{Im}[\tilde{E}]_1 \int_0^{R_1} r dr \int_0^{2\pi} d\phi |E(r, \phi)|^2,
\end{align}

with \(E\) denoting the local electric field.

The configuration under study is characterized by several geometrical and constitutive parameters, which render an exhaustive optimization computationally prohibitive. The designs presented below have been obtained by tweaking a limited number of parameters, until reaching reasonably good performance. Further improvements may be sought, although beyond the interest of the present paper.

#### B. Representative Results

We begin considering the ideal case of lossless cloak and anti-cloak. For a lossy small dielectric target/sensor with radius \(R_1 = \lambda_0/8\) and \(\epsilon_1 = (4 + 0.25)i\lambda_0\), the plots in Fig. 2 illustrate the behavior of the observables of interest, as a function of \(\Delta_2\) and \(\Delta_3\). For \(R_2 = \lambda_0/2\), \(R_3 = (1 + \Delta_3)R_2\), \(R_4 = \lambda_0\), and three representative values of the vacuum gap thickness \(\Delta_G\) in Eq. (13). More specifically, Figs. 2(a)–2(c) and Figs. 2(d)–2(f) show (in decibel scale) the scattering and absorption cross-sectional widths (19), respectively, normalized to their values in vacuum (i.e., in the absence of the cloak/anti-cloak shells), viz.,

\begin{align}
Q_s &= Q_s(0), \quad Q_a = Q_a(0).
\end{align}

From the scattering responses [Figs. 2(a)–2(c)], we observe the presence of a broad minimum, whose position depends on the gap thickness \(\Delta_G\). The case in the absence of gap [Fig. 2(a)] turns out to provide the most substantial scattering reduction (up to over 30 dB below the reference value in vacuum); such a minimum is obtained for the smallest values of \(\Delta_2\) and \(\Delta_3\) in the observation range. Much weaker reductions, and different positions of the minima, are observed in the presence of even a small gap [Figs. 2(b) and 2(c)]. In all three cases, enhancements of the scattering responses (as compared with the reference values in vacuum) can be observed in certain regions; such superscattering phenomena [25] are typical of complementary media, but are not of interest in the present investigation.

The absorption responses [Figs. 2(d)–2(f)] exhibit a slightly more complex structure, with the presence of local minima and maxima, qualitatively similar for the different gap thicknesses. Also in these cases, some superabsorption phenomena [26] are visible, but they are generally associated with the above superscattering effects, and therefore not functional in the sensor-cloaking scenario of interest.

In agreement with the predictions from the analytical study in Section 3, the potentially more interesting responses (especially in terms of scattering reductions) are obtained in the absence of the gap. However, it can be observed that the maximum scattering reduction generally does not coincide with the maximum absorption, and different parameters choices (e.g., increasing the normalized absorption at the expense of the scattering reduction, and vice versa) are possible, as summarized in the trade-off curve (full square markers) in Fig. 3. Such a curve, extracted from Figs. 2(a) and 2(d), for a given value of the (normalized) scattering response yields the largest (normalized) absorption response attainable. In particular, it illustrates how, in the absence of the gap and varying \(\Delta_2\) and \(\Delta_3\), it is possible to span the entire range of cloak/anti-cloak interactions, going from a regime featuring weak scattering and weak absorption (i.e., cloak-prevaling) to one featuring scattering and absorption levels comparable with those in vacuum (i.e., anti-cloak-
prevailing). However, the slope of the curve is such that, in an intermediate regime, one can attain significant scattering reductions (e.g., −20 dB) while maintaining sensible absorption levels (e.g., −1.56 dB). Figure 4 shows a representative field map, from which the very weak overall scattering, and yet the power-coupling capabilities, is fairly visible; as a reference, the case of the target/sensor free-standing in vacuum is shown in Fig. 5.

For comparison purposes, Fig. 3 also shows (full markers) the trade-off curves pertaining to different levels of target losses (Im[\bar{\varepsilon}_3]), from which one notes that loss (and hence mismatch) increases result in a performance degradation (i.e., lower normalized absorption for a given scattering reduction), in accord with our theoretical predictions in Section 3. One might argue that a similar trend (i.e., scattering reduction at the expenses of absorption) is also qualitatively exhibited by an imperfect cloak alone and might therefore wonder to what extent the anti-cloak is strictly necessary and functional. In order to address this issue, Fig. 3 also shows (empty markers) the reference curves pertaining to a TO-based imperfect cloak

![Figure 2](image1)

**Fig. 2.** (Color online) Geometry as in Fig. 1, with \(\varepsilon_1 = (4 + i 0.25)\varepsilon_0\), \(\mu_1 = \mu_0\), \(R_1 = \lambda_0 / 8\), \(R_2 = \lambda_0 / 2\), \(R_3 = (1 + \Delta_g)R_2\), \(\varepsilon_2 = \varepsilon_0\), and lossless cloak and anti-cloak. (a)–(c) Total scattering cross-sectional width in Eq. (19) normalized by the reference value in vacuum [cf. Eq. (21)] in decibel scale, as a function of \(\Delta_g / R_2\) and \(\Delta_2 / R_3\), for gap thicknesses \(\Delta_g = 0, 1/50, 1/25\), respectively. (d)–(f) Corresponding total absorption cross-sectional width normalized by the reference value in vacuum.

![Figure 3](image2)

**Fig. 3.** (Color online) Trade-off curves (full markers) pertaining to the lossless cloak/anti-cloak configuration in Fig. 2, for various values of the target loss levels (squares, circles, triangles, diamonds: \(\text{Im}[\bar{\varepsilon}_3] = 0.25\varepsilon_0\), \(0.5\varepsilon_0\), \(\varepsilon_0\), \(2\varepsilon_0\), respectively). Also shown (empty markers), as references, are the corresponding curves pertaining to an imperfect (lossless) cloak configuration [cf. Eq. (22)].

![Figure 4](image3)

**Fig. 4.** (Color online) Geometry and parameters as in Fig. 2. Field map (real part of magnetic field) pertaining to a plane-wave-excited lossless cloak/anti-cloak configuration with \(\Delta_g = 0\), \(\Delta_g / R_2 = 0.118\), \(\Delta_2 / R_3 = 0.03\), featuring \(\bar{Q}_s = -20\) dB and \(\bar{Q}_\alpha = -1.56\) dB.
scattering reductions only at the expenses of comparable reductions in the absorption.

We also considered more realistic cases involving lossy cloak and anti-cloak shells. More specifically, for the (DPS) cloak shell, we assumed a loss-tangent of 0.001, while for the (DNG) anti-cloak we considered a higher value (0.01). The corresponding scattering and absorption normalized parameters are shown in Fig. 6, with the time-averaged dissipative power in Eq. (20) replacing the absorption cross-sectional width in Eq. (19). As compared with the lossless case above, qualitatively similar results are observed, with an expectable loss-induced moderate deterioration in the performance. Again, the case in the absence of the gap [Figs. 6(a) and 6(d)] turns out to provide the more interesting responses. Figure 7 shows the corresponding trade-off curves, from which, by comparison with the lossless case in Fig. 3, one observes a reduced dynamics in the scattering reduction and a slight increase in the slope. Figure 8 shows a reference field map, for a configuration featuring a scattering reduction of 20 dB at the expense of an absorption reduction of ~3 dB, which qualitatively resembles the lossless case above.

Finally, Fig. 9 shows the effects in the trade-off curves of a further increase in the loss-tangent (0.1) in the (DNG) anti-cloak. Again, further compression in the \( \bar{Q} \) dynamics and increase in the slope are observed. Nevertheless, in spite of the relatively high loss level, in the best-performing case (\( \text{Im}(\varepsilon_1)=0.25\varepsilon_0) \), one can still achieve a scattering reduction of nearly 15 dB at the expense of a reduction of ~4 dB in the absorption. The corresponding field map is shown in Fig. 10.
5. IMPLEMENTATION ISSUES

Although the present prototype study is mainly aimed at providing a proof of principle of the cloak/anti-cloak-based sensor-invisibility effect, it is still important to address the related implementation issues. In particular, for the proposed configuration, the major technological challenges associated with the practical realization of the involved transformation media are related to the spatial inhomogeneity (with extreme values) of all constitutive-parameter components, their general magnetic character, and—most of all—the DNG character of the anti-cloak (in view of the assumed DPS target).

The first two issues are inherent of TO-based cloaks and can be addressed via rigorous or approximate approaches. In particular, higher-order coordinate transformations have been proposed in order to obtain a perfect cloak with spatially invariant axial material parameters [38]. Non-magnetic implementations have also been proposed, based on approximate reductions in the constitutive parameters that preserve the ray trajectories inside the cloak shell (see, e.g., [39–42]) as well as on mapping from a nearly transparent, anisotropic, and spatially inhomogeneous fictitious domain [43].

On the other hand, the last issue (DNG character) is specifically tied with the anti-cloak concept [23], although it may be transferred, in principle, to the target [24]. Nevertheless, we have shown [44] in some preliminary studies on square-type configurations (similar to that originally proposed in [45]) the intriguing possibility of achieving approximate anti-cloaking effects using DPS media only. Extension of these preliminary results to the sensor-cloaking scenario is therefore a key issue and is currently being pursued.

To sum up, a candidate practical implementation may be envisioned as based on the above approximate DPS anti-cloak in conjunction with a suitable parameter reduction approach [38–43]. The study of such a configuration, which would generally require non-trivial modifications in our analytical framework or a fully numerical approach, is beyond the scope of the present prototype study and will be the subject of forthcoming publications.

6. CONCLUSIONS AND PERSPECTIVES

In this paper, we have reported our study of cloak/anti-cloak interactions in 2-D cylindrical geometries, aimed at exploring the potential of such mechanisms in a sensor-cloaking scenario. Via analytical and parametric studies, we have shown that it is possible to tailor the cloak/anti-cloak interactions so as to strongly reduce the scattering
response of a slightly lossy cylindrical target (mimicking a “sensor”) while still allowing effective dissipative power coupling, with a controllable trade-off. Such effects are not destroyed by the presence of slight/moderate losses in the cloak/anti-cloak.

These results lay the foundations for a possible TO-based route to sensor cloaking, alternative to the insofar proposed approaches [32–34]. Within this framework, a comparative study of the various approaches is in order. For instance, one difference that may be expected between our approach (which generally requires DNG resonant metamaterials) and the scattering-cancellation approach in [32] (which is based on inherently penetrable and non-resonant materials) is the presence in our case of a “delay” effect (typical of DNG-based devices) due to the buildup-time of the resonant field in the anti-cloak. Current and future studies are also aimed at removing or mitigating the major technological challenges associated with the practical realization of the involved transformation media (see Section 5), as well as at the extension to the full three-dimensional (vector) scenario.

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